

Resilience in Parallel Programming Environments

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Background

- Resilience is a key challenge in extreme-scale computing
 - Less reliable components
 - More components
 - More dependencies
- Heterogeneity adds significant complexity to the extreme-scale hardware/software ecosystem
 - No fine-grain protection domains & resilience at the component level
 - Coarse-grain checkpoint/restart at the job level is standard



Problem Statement

- The burden for providing resilience is currently on the user
 - Global checkpoint/restart is currently the only practical solution
 - Fault-tolerant MPI is experimental, low-level and <u>maybe</u> in the standard by 2024 at the earliest
 - There are some local checkpoint/restart libraries for accelerators
- A programming model needs to provide resilience with an easy to use interface to permit wide-spread adoption
 - Have clear error & failure models and corresponding abstractions
 - Hide the complexities of protection domains and resilience strategies
 - Offer efficient resilience with little programming burden



Proposed Solution

- Offer an easy to use and generic Quality of Service (QoS) interface for resilience
 - Use abstract, easy to understand, terms and programming constructs
 - Enable users to define their resilience needs
- Establish QoS contracts between the application and the system
 - Offer resilience QoS contract options for <u>accelerator offload</u>
 - Report contract breaches back to the application
- Embed QoS interfaces, coordination mechanisms and resilience strategies in the OpenMP language and runtime
 - An OpenMP that is resilient to accelerator errors/failures: **rOpenMP**



The Quality of Service (QoS) Approach

- Allow application developers to specify their resilience strategy without focusing on the implementation details
- Create a contract that maps application resilience requirements to the underlying hardware/software capabilities
- Specify the resilience strategy without focusing on implementation details



OpenMP QoS language extensions

- **QoS contract:** A set of QoS parameters that reflect resilience requirements by identifying resilience strategies
- QoS parameters: Generic get/set interface, using: (1) key/value pairs, (2) bounded values and (3) ranges of values
- QoS parameter scope: Code block and related data
- **QoS classes:** Offer coherent sets of parameters that achieve popular resilience strategies



#pragma omp qoskv resilience (TASK_REDUNDANCY, BOOL, TRUE)
#pragma omp qoskv resilience (TASK_REDUNDANCY_FACTOR, INT, 3)
#pragma omp qoskv resilience (TASK_REDUNDANCY_MAJORITY, INT, 2)
#pragma omp qoskv resilience (TASK_REDUNDANCY_COMPARE, BOOL, TRUE)
{
 #pragma omp target ...



. . .

}

OpenMP QoS language extensions: QoS classes

#pragma omp qoskv resilience (TASK_TRIPLE_REDUNDANCY, BOOL, TRUE)

#pragma omp target ...



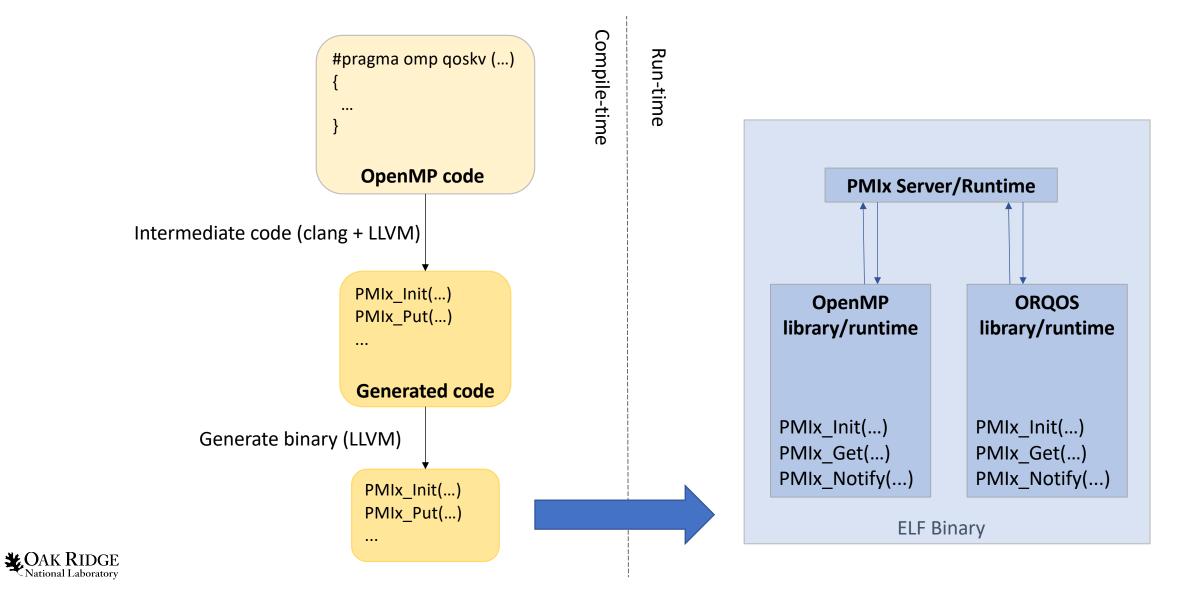
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{

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. . .

Compile-time Workflow and Run-time Interactions of the Implemented Prototype using LLVM 7



- Error and failure detection and notification
 - Detections by the device/OS must be reported to the OpenMP runtime
 - Language feature (such as a callback) for application feedback is needed to potentially decide on the course of action (such as if an error is acceptable or not)
 - Detections by the application must also be reported to the runtime
 - Language feature for raising notifications to the OpenMP runtime is needed as well



- Fail-fast and graceful shutdown
 - Detection, notification and controlled termination as soon as possible
 - Graceful shutdown avoids error propagation and failure cascades
 - Also enables proper error/failure reporting and root-cause analysis
 - Should be the default behavior of OpenMP runtime and applications



Graceful degradation

- Continue operation after an error or failure at the cost of performance or correctness that is deemed acceptable
- May mean to continue with less or slower devices
- Requires runtime support to dynamically remove devices

Rollback recovery

- This we know how to do: Save task data and re-execute if needed
 - VOCL-FT has done this for OpenCL-accelerated applications
- Language feature to limit the maximum number of rollbacks needed



- Redundancy
 - Dual- or triple-redundant execution of tasks
 - Language feature to specify redundancy and type needed
 - Output comparison for error detection and masking
- Redundancy in time
 - Execute the same task at the same time on multiple devices
- Redundancy in space
 - Execute the same task on the same device multiple times



Current Status

✓ Created OpenMP QoS language extensions to describe resilience needs

✓ Developed OpenMP runtime extensions to meet resilience needs

✓ Designed resilience strategies and corresponding protection domains

Christian Engelmann, Geoffroy R. Vallee, and Swaroop Pophale. **Concepts for OpenMP target offload resilience**. 15th International Workshop on OpenMP (IWOMP) 2019, Auckland, New Zealand, September 11-13, 2019. doi: 10.1007/978-3-030-28596-8 6.



Future Work

 \rightarrow Create QoS policies to meet application needs with strategies

 \rightarrow Create the final prototype and demonstrate its capabilities

- Expand the QoS concept to
 - Other OpenMP features
 - Performance, resilience and energy trade-off
 - MPI and MPI+OpenMP
- Create intent-based QoS extensions to be architecture/strategy agnostic
- Develop an adaptive runtime with self-awareness (AI)





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