

ACCELERATED APPLICATIONS AND CONVERGENCE BETWEEN HPC, HPDA AND AI AT CEA

7th ADAC Workshop – ORNL | Christophe CALVIN CEA/DRF | christophe.calvin@cea.fr

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European and French HPC landscape

Big Data – Open data & Open science

Efficient GPU programming

From optimal performances to performances portability

Conclusion



EUROPEAN AND FRENCH HPC LANDSCAPE



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EUROPEAN LANDSCAPE - PRACE





Hazel Hen, GCS@HLRS, Germany Cray XC40 – 7.4 PFlops 185k cores – Intel Haswell



JOLIOT Curie, GENCI@CEA France **BULL SEQUANA – 9.4 PFlops** 56k cores – Intel KNL – 2.5 PFlops



JUWELS, GCS@FZJ, Germany **BULL SEQUANA – 12 PFlops** 79.5k cores – Intel SKL – 6.9 PFlops 122.5k cores – Intel SKL – 10.4 PFlops 192 NVIDIA V100 – 1.6 PFlops



MARCONI, CINECA, Italy Lenovo NeXtScale – 19 PFlops 110k cores – Intel SKL – 8 PFlops 245 k cores – Intel KNL – 11 PFlops



MareNostrum, BSC, Spain 166k cores – Intel SKL – 11 PFlops **Power9+Volta** – 1.5 PFlops Intel KNH – 0.5 PFlops ARM-v8 – 0.5 PFlops



Piz Daint, ETH Zurich/CSCS, Switzerland Cray XC40/XC50 5230 nodes Intel Xeon E5 + P100 – 25 PFlops 1431 nodes Intel Xeon E5 – 1.7 PFlops



SuperMUC-NG, GCS@LRZ, Germany 311 k cores – Intel SKL – 27 PFlops

Over 110 Pflops

- Mainly x86 Intel (>70% ٠ Peak Perf)
- **GPU** (NVIDIA)
- Manycore
- Power
- ARM •

EUROPEAN LANDSCAPE - EUROHPC



The European HPC strategy



The overall strategic goal is to develop a thriving European HPC ecosystem :



Infrastructure: Capacity of acquiring leadership-class computers

<u>Technology</u>: Securing our own independent HPC system supply

<u>Applications</u>: Excellence in HPC applications, and widen HPC use

EuroHPC JU - Objectives



A world-class European HPC, Big Data and Cloud Ecosystem

Co-invest on a leading HPC and data infrastructure

for our scientists, industry and the public sector and support the development of technologies and applications across a wide range of fields

Governing Structure Intelligence gathering Decision making & Advice Implementation



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EUROPEAN LANDSCAPE - EUROHPC



EuroHPC

EuroH	PC – Ac	tivitie	S			The	Infrastructure Pill	ar:			
	~*	nin/Running costs	Infras	 Infrastructure + Operations Acquisition of 2 pre-exascale machines and several (tbd) mid-range machines 			ercomputers				
യ് വ	tions 8		Acquis severa				Precursors to exascale	1	Petascale		
ctur ns	kl, Applica ills		 Applic 	ations & Skills + R&I							
irastru			R&I, ex low-pov	R&I, exascale technologies and systems (incl. low-power processor); applications			At least 2 Precursors to		At least 2 Petascale		
돌 8	R8 Sk	Adn	🔳 JU Adı	 JU Admin/running costs 			exuscule				
HPC Ecosystem		, UL	∎ JI	 JU Operation: 2019 to 2026 			<i>EU contribution:</i> ≤50% of CAPEX and ≤50% of		EU contribution:		
~270	min 180	10	486 m€	EC			OPEX		MAX EU budget: 30 M€		
~290	~186	10	486 m€	Participating States			MAX EU budget: 250 M€				
560	392	20	972 m€	Total							
0	~420 (in kind)	2	422 m€	Private Members	Operations: end 20		perations: end 2020	Operations: mid 202			

Acquistion of 2 exascale systems: 2022/2023

FRENCH LANDSCAPE - GENCI



TGCC



JOLIOT Curie, GENCI@CEA France BULL SEQUANA – 9.4 PFlops 79.5k cores – Intel SKL – 6.9 PFlops 56k cores – Intel KNL – 2.5 PFlops

CINES



OCCIGEN BULL BullX – 3.5 PFlops 85k cores – Intel Haswell

IDRIS



JEAN ZAY HPE – 14 PFlops 60k cores – Intel CascadeLake – 5 Pflops 262 converged nodes - 10k cores + 1k GPUs - 9 PFlops

1 new supercomputer in 2018: Joliot-Curie – SKL + KNL 1 new supercomputer in 2019: Jean Zay – CascadeLake+V100 Extension of Joliot-Curie in 2019: Yet another architecture?

> French researchers may have access up to 120 Pflops But a quite large heterogeneity of architecture No clear vision of future machines (pre-exa and exa)

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BIG DATA – OPEN DATA & OPEN SCIENCE



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DATA: 4TH PILAR OF SCIENCE





- For analysis and data mining
- For data visualization and exploration
- For scholarly communication and dissemination
 - (With thanks to Jim Gray)

OPEN DATA & OPEN SCIENCE

Open Science aims at transforming science **Towards Open Science** through ICT tools, networks and media, to make research more open, global, collaborative, creative and closer to society. Open We are here now Science Open Data & Code Open Access Open Source GitHub Democratization of research Symbiosis Findable Accessible Interoperable Transparent eusable of science, replicable Transformation of science society research and policy New disciplines, new research topics

But implies non-trivial constraints!



Data is becoming another challenge in today science

- Data is coming from many different sources:
 - Observations
 - Numerical simulations
 - Instruments and experiments
- Volume of data is increasing dramatically due to:
 - Needs for finer modeling
 - Progress in HPC usage
 - Instruments giving more and more information
- Interpretation and analysis of these data:
 - Use of HPC \rightarrow HPDA
 - Mixing of many different sources of data
 - Mixing exp./obs data and simulation data
- Data needs to be open and FAIR
 - Complex workflow and dataflow
 - Data have to be accessible + services to explore







CONVERGENCE BETWEEN HPC / BIG DATA / AI



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CONVERGENCE BETWEEN HPC / BIG DATA / AI



HPC for Al Al for HPC Al for data analytics

EUCLID: SEARCHES THE SIGNATURES OF THE DARK ENERGY AND MATTER



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The dark matter and energy can be studied by looking at:

- The geometry of the universe
 - Measure of position of galaxies as a function of redshift
- Growth of density perturbations
 - Evolution of structure as a function of cosmic time, growth rate
- Galaxy image distortion caused by dark matter bending light







How to measure the dark matter:

- EUCLID: measure image distortion
- Cross observations from the ground: measure distances between galaxies
- Correlate these interpreted observational data with numerical simulations
- Use of DL to analyze the images



VGG-16



Simonyan & Zisserman (2018)

Pre-trained network (e.g. using IMAGENET)
 Simple architecture.

CONVERGENCE BETWEEN HPC / BIG DATA / AI



HPC for AI AI for HPC AI for data analytics



EFFICIENT GPU PROGRAMMING



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EXPERIENCES ON GPU PROGRAMMING



RAMSES

- Developped in Saclay to study large scale structure and galaxy formation.
- Flexible package to be used for general purpose simulations in selfgravitating fluid dynamics.

RAMSES-GPU (**MPI** and **GPU** (**CUDA**) parallelisation)

- Finite volume methods for compressible flows (HYDRO and MHD 3D cartesian grids
- Directional splitting Godunov-based, 2nd order for Hydrodynamics
- Unsplit Godunov-based, 2nd order for Hydrodynamics; Rieman solvers are *almost exact* (involves Newtow-Raphson iterations), *HLL*, *HLLC*
- Unsplit Godunov-based, 2nd order for Hydrodynamics
 + Constraint Transport for magnetic field update;
- Riemann solvers for **MHD**are *HLL*, *LLF*, *HLLD*
- Dissipative terms (viscosity, resistivity)
- Self-gravity using a FFT-based Poisson solver





EXPERIENCES ON GPU PROGRAMMING



BigDFT



DFT massively parallel electronic structure code (GPL license) using a wavelet basis set

- First port on GPU NVIDIA using CUDA in 2009
- New version using OpenCL in 2010

Speedur Other

Algorithm	CPU	CUDA	OpenCL	CPU/OpenCL	CUDA/OpenCL
Magic filter	35.7	2.2	1.9	19	1.2
Kinetic	70.2	5.2	3.2	22	1.6
Analysis	33.7	2.3	1.5	22	1.5
Synthesis	43.8	2.3	1.6	28	1.5
Uncompress	195	20.3	10.5	19	2.1
Compress	100	13.6	7.6	13	1.8





- Included in a docker-container
- Could be run on a Bare Metal server or on NVIDIA GPU Cloud





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CSCS Todi, benefit of GPU usage



Chapman & Hall/CRC Computational Science Series

Exascale Scientific Applications

Scalability and Performance Portability

Edited by Tjerk P. Straatsma Katerina B. Antypas Timothy J. Williams

CRC Press

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FROM OPTIMAL PERFORMANCES TO PERFORMANCES PORTABILITY

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Multi-architecture implementation of Spectral Difference Methods (SDM) for compressible flows using performance porta ble programing tools (c++ kokkos)

Pierre Kestener

CEA Saclay, DRF, Maison de la Simulation, FRANCE

Seminar CERFACS, Toulouse, February 15th, 2019



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PERFORMANCE PORTABILITY

- Developing / maintaining a separate implementation of an application for each new hardware platform(Intel KNL, Nvidia GPU, ARMv8, ...) is less and less realistic
- Identical code will never perform optimally on all platforms
- Is it possible to have a **single set of source codes** that can be compiled for different hardware targets ?
- Performance portability should be understood as a single source code base with
 - **___ good** performance on different architecture
 - a relatively **small amount of effort** required to tune app performance from one architecture to another.
 - source http://www.nersc.gov/research-and-development/application-readiness-across-doe-labs
- **Low-level native language:** OpenCL, CUDA, ...
- **Directive approach (code annotations)** for multicore/GPU (OpenMP 4.5, OpenACC 2.5)
- Other high-level library-based approaches (mostly c++-based, à la TBB):
 - Some provide STL-like algorithmics patterns (Thrust, lift, arrayFire)
 - Kokkos, RAJA, ...
 - Cross-platform frameworks (Chamm++, hpx)
- **Use an embedded Domain Specific Language (DSL) (**Halide, NABLA)

RAMSESGPU WITH KOKKOS

Astrophysics motivations - HPC applications CPU/GPU performances

What is MRI (Magneto-rotational instability) ? High resources requirements : need for GPU acceleration Compressible (M)HD and finite volume methods

Directionally splitted Hydro - 3D performances

Number of 10⁶ cell updates / second versus domain size

taille	M2090			K20		
	SP/fast	SP	DP	SP/fast	SP	DP
32x32x32	18.8			26.6 (+41%)		
64x64x64	83.4			95.2 (+14%)		
96x96x96	100.7		\frown	175.1 (+73%)		\frown
128x128x128	114.7	32.1	(9.2)	178.7 (+55%)	72.4 ((34.9)
192x192x192	133.0		\sim	226.7 (+70%)		\sim
225x225x225	137.2	39.5	(11.1)	210.5 (+53%)	97.4	(40.6)

- Architecture Kepler K20 versus Fermi M2090
- Rebuild application with CUDA 5.5 toolchain for architecture 3.5 and tune flags
- Tune max register count for Kepler, and care about *read-only data cache* ==> No more register spilling, DP perf is optimal !
- in DP : Kepler is ~ 3.5× faster than than M2090

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- With Kokkos, from Kepler K80 ⇒ Pascal P100, performance scaling almost perfect (~ ×3.0); no tuning required ; 360 Mcell-update/s
- With hand-written CUDA, tuning is required to recover this perf scaling
- Number of lines of codes divided by 2-3
- Get for free an efficient OpenMP implementation

SDM PERFORMANCES ON VARIOUS ARCHITECTURE USING KOKKOS



SKL vs GPU

SKL vs ARM vs GPU

Power8 vs GPU

Illustration on MC neutron transport code (PATMOS – CEA/DEN)

- Main kernel: XS calculation
- 2 benchmarks: S1Bench & PATMOS
- 2 versions: History Based (HB) & Pseudo Event Based (PEB)

The principle of MC transport for Neutrons :

- Follow each particle from birth to absorption or leakage (history).
- Governed by interaction probabilities described by microscopic cross sections

Madal	Compilor	S1B	ench	PATMOS		
Model	Compilei	HB	PEB	HB	PEB	
MPI+OMPth	GCC,PGI,XLC,Clang	\checkmark	\checkmark	\checkmark	\checkmark	
MPI+OMPth+CUDA	GCC,PGI,XLC,Clang	\checkmark	\checkmark	\checkmark	\checkmark	
MPI+OMPth+OACC	PGI	\checkmark	\checkmark	\checkmark	\checkmark	
MPI+OMPth+OMP	XLC	\checkmark	\checkmark	\checkmark	\checkmark	
MPI+OMPth+Kokkos	GCC	\checkmark	\checkmark	\checkmark	\checkmark	
MPI+OCCA	GCC					

Table: Programming model





Cross sections depending on energy

T. Chang, E. Brun, F. Malvagi, C. Calvin

PORTABITLITY METRICS

Metric

- $p = \frac{L_{TDA}}{L_T}$, where
 - *L_{TDA}*: Total lines used across different architectures
 - L_T : Total lines

Metric

D

$\mathbf{P}(\mathbf{H}) = \mathbf{H} $ where \int	Н	a set of platforms
$\mathbf{r}(\mathbf{n}) = \frac{1}{\sum_{i=1}^{n}}, \text{ where } \{$	e _i	performance efficiency on H _i
$L_{i \in H}$		

$\mathcal{L}_{i\in H}\overline{\mathbf{e}_{i}}$	{H} = {CPU, GPU}					
	Version	Ltda	Lτ	Portability (%)		
	OMPth	0	247	0		
fficulty	CUDA	0	237	0		
 Hard to measure performance efficiency e_i: Deals performance, such as STLODG 	OpenACC	265	265	100		
 It is difficult to measure performances of \$1Bench and 	OpenMP	263	263	100		
PATMOS in terms of GFLOPs	Kokkos	10	275	96		
	OCCA	2	270	99		



CONCLUSION

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CONCLUSION

- It is not a novelty: architecture are more and more complex
- Which is new: workflow are more and more complex, mixing HPC, HPDA, AI ...
- Data is becoming the corner stone of the system (and system of systems edge computing, fog computing ...)
- Convergence between HPC, HPDA and AI is coming from usages, not from HW or SW solutions
 - \rightarrow from a user point-of-view the landscape is becoming more and more complex
- From the HPC point-of-view (which has been partially addressed in this talk), one major concerns is performance portability: provide to developers framework, tools, methodologies to deal with all these complexities in a constantly evolving environment.



THANK YOU !

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