HPC + AI

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PRACTICAL DEEP LEARNING EXAMPLES



Image Classification, Object Detection, Localization, Action Recognition, Scene Understanding



Speech Recognition, Speech Translation, Natural Language Processing



Pedestrian Detection, Traffic Sign Recognition



Breast Cancer Cell Mitosis Detection, Volumetric Brain Image Segmentation

WHAT IS DEEP LEARNING?



NVIDIA DEEP LEARNING SOFTWARE PLATFORM





developer.nvidia.com/deep-learning-software

NVIDIA DEEP LEARNING SDK

High performance GPU-acceleration for deep learning

Powerful tools and libraries for designing and deploying GPU-accelerated deep learning applications

High performance building blocks for training and deploying deep neural networks on NVIDIA GPUs

Industry vetted deep learning algorithms and linear algebra subroutines for developing novel deep neural networks

Multi-GPU and multi-node scaling that accelerates training to hundred of GPUs



"We are amazed by the steady stream of improvements made to the NVIDIA Deep Learning SDK and the speedups that they deliver."

NVIDIA Collective Communications Library (NCCL) 2

Multi-GPU and multi-node collective communication primitives

High-performance multi-GPU and multi-node collective communication primitives optimized for NVIDIA GPUs

Fast routines for multi-GPU multi-node acceleration that maximizes inter-GPU bandwidth utilization

Easy to integrate and MPI compatible. Uses automatic topology detection to scale HPC and deep learning applications over PCIe and NVink

Accelerates leading deep learning frameworks such as Caffe2, Microsoft Cognitive Toolkit, MXNet, PyTorch and more



Multi-GPU: NVLink PCIe



Multi-Node: InfiniBand verbs IP Sockets



Automatic Topology Detection

RESNET-50 FP32 PERFORMANCE

■ Series1 ■ Series2 ■ Series3 ■ Series4 ■ Series5 ■ Series6 ■ Series7



NVIDIA TensorRT

Deep Learning Inference Optimizer and Runtime

High performance neural network inference optimizer and runtime engine for production deployment

Maximize inference throughput for latency-critical services in hyperscale datacenters, embedded, and automotive production environments.

Optimize models trained in TensorFlow or Caffe to generate runtime engines that maximizes inference throughput

Deploy faster, more responsive and memory efficient deep learning applications with INT8 and FP16 optimized precision support



TensorRT 3: 3.5X FASTER INFERENCE

3.5x Faster Inference For Real-Time Latency-Critical Services



ResNet50 Inference, TensorRT performance (images/sec), TensorRT + K80: Batch Size =1, Latency = 10 ms TensorRT + P100 (FP16): Batch Size =9 Latency= 7ms, TensorRT + V100 (FP16): Batch Size =26 Latency= 7ms,

developer.nvidia.com/tensorrt

FACTORS DRIVING HISTORIC CHANGES IN HPC





End of Dennard Scaling places a cap on single threaded performance

Increasing application performance will require fine grain parallel code with significant computational intensity

Al and Data Science emerging as important new components of scientific discovery

Dramatic improvements in accuracy, completeness and response time yield increased insight from huge volumes of data

Cloud based usage models, in-situ execution and visualization emerging as new workflows critical to the science process and productivity

Tight coupling of interactive simulation, visualization, data analysis/AI



THE EX FACTOR IN THE EXASCALE ERA

Multiple Experiments Coming or Upgrading In the Next 10 Years











THE POTENTIAL OF EXASCALE HPC + AI

HPC	Al
+40 years of Algorithms based on first principles theory Proven statistical models for accurate results in multiple science domains	New methods to improve predictive accuracy, insight into new phenomena and response time with previously unmanageable data sets
Commercially viable fusion energy	
Understanding the Origins of the Universe	
Clinically Viable Precision Medicine	

Improve/validate the Standard Model of Physics

Climate/Weather forecasts with ultra high fidelity

TAXONOMY Examples of HPC + AI Convergence

Real Time Enhancement(A): Experimental Data used to Train a NN which improves detection accuracy/latency for real time use Extension: Experimental / Simulated Data used to Train a NN that extends fidelity of simulation

Breakthrough Opportunities

Real Time Enhancement(B): Simulated Data used to Train a NN which improves detection accuracy/latency for real time use

Parameterization: Experimental / Simulated Data used to Train a NN which steers simulation within/btwn runs Augmentation: Experimental / Simulated Data used to Train a NN that replaces part of a simulation

> Replacement: Experimental / Simulated Data used to Train a NN that replaces a simulation



Despite the latest development in computational power, there is still a large gap in linking relativistic theoretical models to observations. Max Plank Institute



MULTI-MESSENGER ASTROPHYSICS

Background

The aLIGO (Advanced Laser Interferometer Gravitational Wave Observatory) experiment successfully discovered signals proving Einstein's theory of General Relativity and the existence of cosmic Gravitational Waves. While this discovery was by itself extraordinary it is seen to be highly desirable to combine multiple observational data sources to obtain a richer understanding of the phenomena.

Challenge

The initial a LIGO discoveries were successfully completed using classic data analytics. The processing pipeline used hundreds of CPU's where the bulk of the detection processing was done offline. Here the latency is far outside the range needed to activate resources, such as the Large Synaptic Space survey Telescope (LSST) which observe phenomena in the electromagnetic spectrum in time to "see" what aLIGO can "hear".

Solution

A DNN was developed and trained using a data set derived from the CACTUS simulation using the Einstein Toolkit. The DNN was shown to produce better accuracy with latencies 1000x better than the original CPU based waveform detection.

Impact

Faster and more accurate detection of gravitational waves with the potential to steer other observational data sources.



Predicting Disruptions in Fusion Reactor using DL

Background

Grand challenge of fusion energy offers mankind changing opportunity to provide clean, safe energy for millions of years. ITER is a \$25B international investment in a fusion reactor.

Challenge

Fusion is highly sensitive, any disruption to conditions can cause reaction to stop suddenly. Challenge is to predict when a disruption will occur to prevent damage to ITER and to steer the reaction to continue to produce power. Traditional simulation and ML approaches don't deliver accurate enough results.

Solution

DL network called FRNN using Theano exceeds today's best accuracy results. It scales to 200 Tesla K20s, and with more GPUs, can deliver higher accuracy. Goal is to reach 95% accuracy.

Impact

Vision is to operate ITER with FRNN, operating and steering experiments in realtime to minimize damage and down-time.





Al Quantum Breakthrough

Background

Developing a new drug costs \$2.5B and takes 10-15 years. Quantum chemistry (QC) simulations are important to accurately screen millions of potential drugs to a few most promising drug candidates.

Challenge

QC simulation is computationally expensive so researchers use approximations, compromising on accuracy. To screen 10M drug candidates, it takes 5 years to compute on CPUs.

Solution

Researchers at the University of Florida and the University of North Carolina leveraged GPU deep learning to develop ANAKIN-ME, to reproduce molecular energy surfaces with super speed (microseconds versus several minutes), extremely high (DFT) accuracy, and at 1-10/millionths of the cost of current computational methods.

Impact

Faster, more accurate screening at far lower cost







FINDING THE "GHOST PARTICLE" WITH AI

Background

The NoVA experiment managed by Fermi lab comprises 200 scientists at 40 institutions in 7 countries. The goal is to track neutrino's, which are often referred to as the "Ghost Particle", and detect oscillation which is used to better understand how this super abundant, and elusive particle interacts with matter.

Challenge

The experiment is built underground and is comprised of a main injector beam and two large detector apparatus located 50 miles apart. The near detector is 215 Tons and the Far detector is 15,000 Tons. The experiment can be thought of as a 30 Mn pound detector that takes 2 Mn pictures per second.



The detectability of the current experiment is proportional to the size of the detectors, so increasing the "visibility" is complex and costly.

Solution

A DNN was developed and trained using a data set derived from multiple HPC simulations including GENIE and GEANT using 2 K40 GPU's. The CVN was based on convolutional neural networks used for image processing

Impact

The result was an overall improvement of 33%, where the optimized CVN signal-detectionoptimized efficiency of 49% is a significant gain over the efficiency of 35% quoted in prior art. This would net to a 10Mn pound increase the physical detector



Forecasting Fog at Zurich Airport

Background

Unexpected fog can cause an airport to cancel or delay flights, sometimes having global effects in flight planning.

Challenge

While the weather forecasting model at MeteoSwiss work at a 2km x 2km resolution, runways at Zurich airport is less than 2km. So human forecasters sift through huge simulated data with 40 parameters, like wind, pressure, temperature, to predict visibility at the airport.

Solution

MeteoSwiss is investigating the use of deep learning to forecast type of fog and visibility at sub-km scale at Zurich airport.





Earthquake Prediction

Multiple Examples of AI for earthquake prediction are underway

Shaazam for Earthquakes



SCIENTIFIC AMERICAN₈

Can Artificial Intelligence Predict Earthquakes?

COMPUTING

The ability to forecast temblors would be a tectonic shift in seismology. But is it a pipe dream? A seismologist is conducting machine-learning experiments to find out









